

Inter Task Communication

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- Task to Task

Communication Type

- Task to Task
- Task to Interrupt Service Routine (ISR)

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- ISR to Task

Queue in FreeRTOS

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- Queues are normally used as First In First Out (FIFO) buffers, where data is written to the end (tail) of the queue and removed from the front (head) of the queue.

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Queue Implementation

- **Queue by copy:** The data sent to the queue is copied byte for byte into the queue. *FreeRTOS uses the queue by copy method.*
- **Queue by reference:** Queues only holds pointers to the data sent to the queue, not the data itself.

Pros

- Stack variables can be sent directly to a queue, even though the variables will not exist after the related function has exited.
- The sending task can immediately re-use the variable or buffer that was sent to the queue.
- Queuing by copy does not prevent the queue from also being used to queue by reference.
- The RTOS takes complete responsibility for allocating the memory used to store data.

Queue by Copy

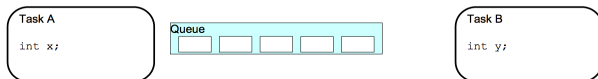
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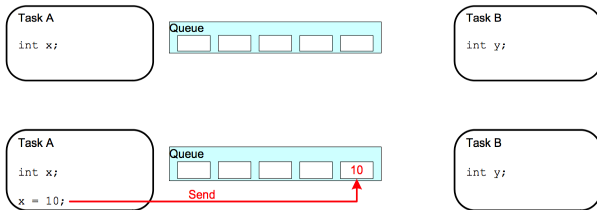
Cons

If the size of the data being stored in the queue is large, then it is preferable to use the queue to transfer pointers to the data, rather than copy the data itself into and out of the queue byte by byte.

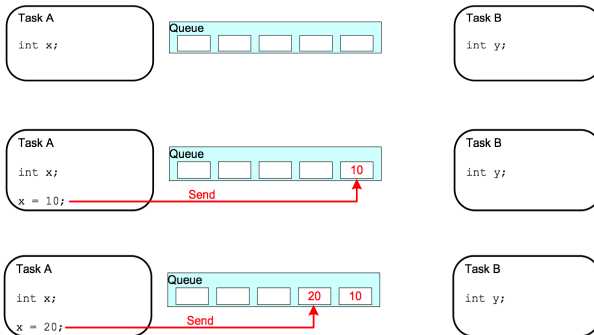
How Does Queue-based Communication work?



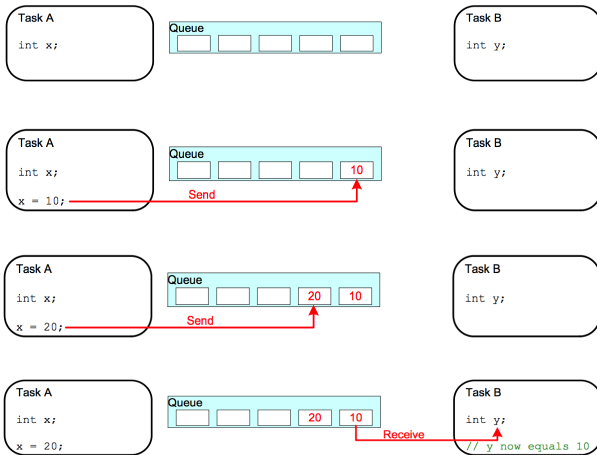
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Create a Queue

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Return values of the function:

- **NULL**: the queue has not been created successfully because of insufficient heap memory.
- **non-NULL**: the queue has been created and the queue handle is returned.

Blocking on Queue Reads

- A task can specify a 'block' time when reading from a queue. This is the time the task will be kept in the Blocked state to wait for data to be available from the queue.
- The task be moved to the Ready state when data is written into the queue. It also is moved from the Blocked state to the Ready state if the specified block time expires before data becomes available.
- If a Queue has multiple readers, only one task (highest priority task) will be unblocked when data becomes available. If blocked tasks have equal priority, then the task that with longest waiting time will be unblocked.

Blocking on Queue Reads

Similarly, tasks can specify blocking time for writing in a queue.

Send a Message

```
xQueueSend*( QueueHandle_t xQueue, const void *  
             pvItemToQueue, TickType_t xTicksToWait )
```

Description

`xQueueSendToBack()` sends data to the back (tail) of a queue.

`xQueueSendToFront()` sends data to the front (head) of a queue.

`xQueueSend()` is equivalent to `xQueueSendToBack()`.

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<i>xQueue</i>	the handle of the queue.
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Return values of the function:

- `pdPASS`: data was successfully sent to the queue.
- `errQUEUE_FULL`: data could not be written to the queue because the queue was already full.

Receive a Message

```
 BaseType_t xQueueReceive( QueueHandle_t xQueue, void * const  
    pvBuffer, TickType_t xTicksToWait );
```

Description

`xQueueReceive()` receives (read) an item from a queue. *The received item is removed from the queue.*

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<code>xTicksToWait</code>	the maximum amount of time the task should remain in the Blocked state.

Return values of the function:

- `pdPASS`: data was successfully read from the queue.
- `errQUEUE_EMPTY`: data cannot be read from the queue because the queue is already empty.


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UBaseType_t uxQueueMessagesWaiting( QueueHandle_t xQueue );
```

Description

`uxQueueMessagesWaiting` queries the number of items that are currently in a queue.

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<i>xQueue</i>	the handle of the queue.

Example: Create Queues

```
QueueHandle_t xQueue;  
int main( void ){  
    /* The queue is created to hold a maximum of 5 values, each  
       of which is large enough to hold a variable of type  
       int32_t. */  
    xQueue = xQueueCreate( 5, sizeof( int32_t ) );  
    if( xQueue != NULL ){  
        // rest of the code  
    }  
    else{  
        //The queue could not be created.  
    }  
    for( ;; );  
}
```

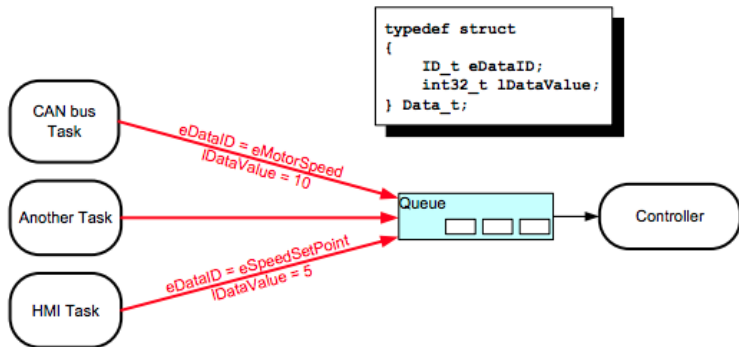
Example: Write to a Queues

```
void vSenderTask( void *pvParameters ){
    int32_t lValueToSend;
    BaseType_t xStatus;
    lValueToSend = ( int32_t ) pvParameters;
    for( ;; ){
        xStatus = xQueueSendToBack( xQueue , &lValueToSend , 0 );
        if( xStatus != pdPASS ){
            vPrintString( "Could not send to the queue.\r\n" );
        }
    }
}
```

Example: Read from a Queues

```
static void vReceiverTask( void *pvParameters ){
    int32_t lReceivedValue;
    BaseType_t xStatus;
    const TickType_t xTicksToWait = pdMS_TO_TICKS( 100 );
    for( ;; )
    {
        xStatus = xQueueReceive( xQueue, &lReceivedValue,
                                xTicksToWait );
        if( xStatus == pdPASS ){
            vPrintStringAndNumber( "Received = ", lReceivedValue );
        }
        else{
            vPrintString( "Could not receive from the queue.\r\n" );
        }
    }
}
```

Receiving Data From Multiple Sources



Receiving Data From Multiple Sources

```
/* Define an enumerated type used to identify the source of  
the data. */  
typedef enum{  
    eSender1,  
    eSender2  
} ID_t;  
  
//Define the structure type that will be passed on the queue  
  
typedef struct{  
    uint8_t edataValue;  
    ID_t eDataSource;  
} Data_t;  
  
// create a queue  
xQueue = xQueueCreate( 3, sizeof( Data_t ) );
```

Receiving Data From Multiple Sources

```
xStatus = xQueueReceive( xQueue, &xReceivedStructure, 0 );
if( xStatus == pdPASS ){
    if( xReceivedStructure.eDataSource == eSender1 {
        vPrintStringAndNumber( "From Sender 1 = ",
            xReceivedStructure.edataValue );
    }
    else{
        vPrintStringAndNumber( "From Sender 2 = ",
            xReceivedStructure.edataValue );
    }
}
```


Create a Mailbox

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Overwrite Data in queue

`xQueueOverwrite()` API can be used to overwrite data in a queue.

```
xQueueOverwrite( QueueHandle_t xQueue, const void * pvItemToQueue )
```

Read Data without Remove

`xQueuePeek()` API can be used to read data in a queue without removing it.

```
xQueuePeek( QueueHandle_t xQueue, void * const pvBuffer, TickType_t  
xTicksToWait );
```

Question?